

Bicategories of Diffeological Groupoids

Jordan Watts

Central Michigan University

July 19, 2022

Jordan Watts, “Bicategories of diffeological groupoids”,
<https://arxiv.org/abs/2206.12730>

Why Study Diffeological Groupoids?

- They appear in the work of Blohmann, Fernandes, and Weinstein on general relativity, in which a diffeological groupoid describes the choices of embeddings of an initial space-like hypersurface in a lorentzian spacetime, up to a prescribed equivalence [BFW13].
- They show up naturally in the study of singular subalgebroids of Lie algebroids, and related, the holonomy and fundamental groupoids of singular foliations [AZ20, GV21].
- Presentations of “higher geometric” loop spaces (*i.e.* loop stacks) are presented by diffeological groupoids [RV18]; in fact, these groupoids are Fréchet-Lie groupoids.
- Inertia groupoids of Lie groupoids and relation groupoids of equivalence relations are typically not Lie groupoids, but they are diffeological groupoids.

Why Study Diffeological Groupoids?

- They appear in the work of Blohmann, Fernandes, and Weinstein on general relativity, in which a diffeological groupoid describes the choices of embeddings of an initial space-like hypersurface in a lorentzian spacetime, up to a prescribed equivalence [BFW13].
- They show up naturally in the study of singular subalgebroids of Lie algebroids, and related, the holonomy and fundamental groupoids of singular foliations [AZ20, GV21].
- Presentations of “higher geometric” loop spaces (*i.e.* loop stacks) are presented by diffeological groupoids [RV18]; in fact, these groupoids are Fréchet-Lie groupoids.
- Inertia groupoids of Lie groupoids and relation groupoids of equivalence relations are typically not Lie groupoids, but they are diffeological groupoids.

Why Study Diffeological Groupoids?

- They appear in the work of Blohmann, Fernandes, and Weinstein on general relativity, in which a diffeological groupoid describes the choices of embeddings of an initial space-like hypersurface in a lorentzian spacetime, up to a prescribed equivalence [BFW13].
- They show up naturally in the study of singular subalgebroids of Lie algebroids, and related, the holonomy and fundamental groupoids of singular foliations [AZ20,GV21].
- Presentations of “higher geometric” loop spaces (*i.e.* loop stacks) are presented by diffeological groupoids [RV18]; in fact, these groupoids are Fréchet-Lie groupoids.
- Inertia groupoids of Lie groupoids and relation groupoids of equivalence relations are typically not Lie groupoids, but they are diffeological groupoids.

Why Study Diffeological Groupoids?

- They appear in the work of Blohmann, Fernandes, and Weinstein on general relativity, in which a diffeological groupoid describes the choices of embeddings of an initial space-like hypersurface in a lorentzian spacetime, up to a prescribed equivalence [BFW13].
- They show up naturally in the study of singular subalgebroids of Lie algebroids, and related, the holonomy and fundamental groupoids of singular foliations [AZ20, GV21].
- Presentations of “higher geometric” loop spaces (*i.e.* loop stacks) are presented by diffeological groupoids [RV18]; in fact, these groupoids are Fréchet-Lie groupoids.
- Inertia groupoids of Lie groupoids and relation groupoids of equivalence relations are typically not Lie groupoids, but they are diffeological groupoids.

Why Study Diffeological Groupoids?

- They appear in the work of Blohmann, Fernandes, and Weinstein on general relativity, in which a diffeological groupoid describes the choices of embeddings of an initial space-like hypersurface in a lorentzian spacetime, up to a prescribed equivalence [BFW13].
- They show up naturally in the study of singular subalgebroids of Lie algebroids, and related, the holonomy and fundamental groupoids of singular foliations [AZ20,GV21].
- Presentations of “higher geometric” loop spaces (*i.e.* loop stacks) are presented by diffeological groupoids [RV18]; in fact, these groupoids are Fréchet-Lie groupoids.
- Inertia groupoids of Lie groupoids and relation groupoids of equivalence relations are typically not Lie groupoids, but they are diffeological groupoids.

What Has Been Done So Far?

- A rigorous foundation for diffeological groupoids using so-called “bibundles” was written by NESTA van der Schaaf in his Master’s thesis [vdS20] and subsequent paper [vdS21].
- An open question from his work was whether a so-called diffeological Morita equivalence between Lie groupoids was in fact a Lie Morita equivalence. (*i.e.* Do groupoids coming from the realm of smooth manifolds fit into the diffeological theory as one would hope?)
- In this work being presented, I answer this open question (in the affirmative), but instead of using bibundles, I use a slightly more categorical approach.

What Has Been Done So Far?

- A rigorous foundation for diffeological groupoids using so-called “bibundles” was written by Nesta van der Schaaf in his Master’s thesis [vdS20] and subsequent paper [vdS21].
- An open question from his work was whether a so-called diffeological Morita equivalence between Lie groupoids was in fact a Lie Morita equivalence. (*i.e.* Do groupoids coming from the realm of smooth manifolds fit into the diffeological theory as one would hope?)
- In this work being presented, I answer this open question (in the affirmative), but instead of using bibundles, I use a slightly more categorical approach.

What Has Been Done So Far?

- A rigorous foundation for diffeological groupoids using so-called “bibundles” was written by Nesta van der Schaaf in his Master’s thesis [vdS20] and subsequent paper [vdS21].
- An open question from his work was whether a so-called diffeological Morita equivalence between Lie groupoids was in fact a Lie Morita equivalence. (*i.e.* Do groupoids coming from the realm of smooth manifolds fit into the diffeological theory as one would hope?)
- In this work being presented, I answer this open question (in the affirmative), but instead of using bibundles, I use a slightly more categorical approach.

What Has Been Done So Far?

- A rigorous foundation for diffeological groupoids using so-called “bibundles” was written by NESTA van der Schaaf in his Master’s thesis [vdS20] and subsequent paper [vdS21].
- An open question from his work was whether a so-called diffeological Morita equivalence between Lie groupoids was in fact a Lie Morita equivalence. (*i.e.* Do groupoids coming from the realm of smooth manifolds fit into the diffeological theory as one would hope?)
- In this work being presented, I answer this open question (in the affirmative), but instead of using bibundles, I use a slightly more categorical approach.

Diffeological Spaces

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Diffeological Spaces

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Diffeological Spaces

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Diffeological Spaces

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Diffeological Spaces

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Fix a set X .

Definition

A **parametrisation** of X is a function $p: U \rightarrow X$ where U is a Euclidean open set (no particular dimension).

A **diffeology** on X is a family \mathcal{D} of parametrisations of X satisfying:

- 1 all constant maps $U \rightarrow X$ are in \mathcal{D} ;
- 2 given $p: U \rightarrow X$ for which there is an open cover $\{U_\alpha\}$ of U , and for each α a parametrisation $p_\alpha \in \mathcal{D}$ such that $p_\alpha = p|_{U_\alpha}$, then $p \in \mathcal{D}$;
- 3 if $f: V \rightarrow U$ is smooth with V a Euclidean open set and $(p: U \rightarrow X) \in \mathcal{D}$, then $p \circ f \in \mathcal{D}$.

We call (X, \mathcal{D}) a **diffeological space**, and parametrisations $p \in \mathcal{D}$ **plots**.

Definition

A function $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is **(diffeologically) smooth** if for every $p \in \mathcal{D}_X$,

$$F \circ p \in \mathcal{D}_Y.$$

- Diffeological spaces with smooth maps form a category $\mathbf{Diffeol}$ which is a complete and cocomplete quasi-topos. In particular, subsets, quotients, products, coproducts, function spaces, etc., all have natural diffeological structures.
- $\mathbf{Diffeol}$ contains the category of smooth manifolds (as a full subcategory), effective orbifolds, orbit spaces, etc.

Definition

A function $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is **(diffeologically) smooth** if for every $p \in \mathcal{D}_X$,

$$F \circ p \in \mathcal{D}_Y.$$

- Diffeological spaces with smooth maps form a category **Diffeol** which is a complete and cocomplete quasi-topos. In particular, subsets, quotients, products, coproducts, function spaces, etc., all have natural diffeological structures.
- **Diffeol** contains the category of smooth manifolds (as a full subcategory), effective orbifolds, orbit spaces, etc.

Definition

A function $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is **(diffeologically) smooth** if for every $p \in \mathcal{D}_X$,

$$F \circ p \in \mathcal{D}_Y.$$

- Diffeological spaces with smooth maps form a category **Diffeol** which is a complete and cocomplete quasi-topos. In particular, subsets, quotients, products, coproducts, function spaces, etc., all have natural diffeological structures.
- **Diffeol** contains the category of smooth manifolds (as a full subcategory), effective orbifolds, orbit spaces, etc.

Definition

A function $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is **(diffeologically) smooth** if for every $p \in \mathcal{D}_X$,

$$F \circ p \in \mathcal{D}_Y.$$

- Diffeological spaces with smooth maps form a category **Diffeol** which is a complete and cocomplete quasi-topos. In particular, subsets, quotients, products, coproducts, function spaces, etc., all have natural diffeological structures.
- **Diffeol** contains the category of smooth manifolds (as a full subcategory), effective orbifolds, orbit spaces, etc.

Subductions

Definition

A smooth surjection $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **subduction** if for every plot $p: U \rightarrow Y$ of Y , there is an open cover $\{U_\alpha\}$ of U and for each α a plot $q_\alpha: U_\alpha \rightarrow X$ such that

$$p|_{U_\alpha} = F \circ q_\alpha.$$

Definition

A subduction $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **local subduction** if for every plot $p: U \rightarrow Y$, every $u \in U$, and every $x \in F^{-1}(p(u))$, there is an open neighbourhood $V \subseteq U$ of u and a plot $q: V \rightarrow X$ of X so that $p|_V = F \circ q$ and $q(u) = x$.

Exercise

A map between manifolds is a local subduction if and only if it is a surjective submersion.

Subductions

Definition

A smooth surjection $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **subduction** if for every plot $p: U \rightarrow Y$ of Y , there is an open cover $\{U_\alpha\}$ of U and for each α a plot $q_\alpha: U_\alpha \rightarrow X$ such that

$$p|_{U_\alpha} = F \circ q_\alpha.$$

Definition

A subduction $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **local subduction** if for every plot $p: U \rightarrow Y$, every $u \in U$, and every $x \in F^{-1}(p(u))$, there is an open neighbourhood $V \subseteq U$ of u and a plot $q: V \rightarrow X$ of X so that $p|_V = F \circ q$ and $q(u) = x$.

Exercise

A map between manifolds is a local subduction if and only if it is a surjective submersion.

Subductions

Definition

A smooth surjection $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **subduction** if for every plot $p: U \rightarrow Y$ of Y , there is an open cover $\{U_\alpha\}$ of U and for each α a plot $q_\alpha: U_\alpha \rightarrow X$ such that

$$p|_{U_\alpha} = F \circ q_\alpha.$$

Definition

A subduction $F: (X, \mathcal{D}_X) \rightarrow (Y, \mathcal{D}_Y)$ is a **local subduction** if for every plot $p: U \rightarrow Y$, every $u \in U$, and every $x \in F^{-1}(p(u))$, there is an open neighbourhood $V \subseteq U$ of u and a plot $q: V \rightarrow X$ of X so that $p|_V = F \circ q$ and $q(u) = x$.

Exercise

A map between manifolds is a local subduction if and only if it is a surjective submersion.

Subductions

Exercise

A map is a diffeomorphism if and only if it is an injective subduction.

Example

The smooth map $\mathbb{R} \amalg \mathbb{R} \rightarrow \mathbb{R}$ which is constant (say, equal to 0) on the first copy of \mathbb{R} , but equal to the identity on the second copy of \mathbb{R} , is a subduction. However, it is not a local subduction.



Subductions

Exercise

A map is a diffeomorphism if and only if it is an injective subduction.

Example

The smooth map $\mathbb{R} \amalg \mathbb{R} \rightarrow \mathbb{R}$ which is constant (say, equal to 0) on the first copy of \mathbb{R} , but equal to the identity on the second copy of \mathbb{R} , is a subduction. However, it is not a local subduction.



Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Definition

A groupoid \mathcal{G} (or $\mathcal{G}_1 \rightrightarrows \mathcal{G}_0$) is a (small) category in which all of the morphisms are invertible.

- The **objects** are denoted \mathcal{G}_0 ;
- the **arrows** are denoted \mathcal{G}_1 ;
- the **source map**, denoted s , sends an arrow $x \xrightarrow{g} x'$ to object x ;
- the **target map**, denoted t , sends an arrow $x \xrightarrow{g} x'$ to object x' ;
- the **unit map**, denoted u , sends an object x to its identity morphism u_x ;
- the **multiplication map**, denoted m , is the composition of the category, sending (g, g') to $g'g$;
- the **inversion map**, denoted inv , sends an arrow g to its inverse g^{-1} .

Examples

- A group G is a groupoid with one object, and whose arrows are exactly G .
- A set X can be perceived as a **trivial groupoid** whose objects are the points of X and arrows are exactly the corresponding units.
- Given a set X , the **pair groupoid** is the groupoid whose objects are points of X and arrows are all pairs (x, x') in $X \times X$.
- Given an equivalence relation \sim on a set X , the **relation groupoid** R has objects points of X , with an arrow between x and x' if $x \sim x'$.

Examples

- A group G is a groupoid with one object, and whose arrows are exactly G .
- A set X can be perceived as a **trivial groupoid** whose objects are the points of X and arrows are exactly the corresponding units.
- Given a set X , the **pair groupoid** is the groupoid whose objects are points of X and arrows are all pairs (x, x') in $X \times X$.
- Given an equivalence relation \sim on a set X , the **relation groupoid** R has objects points of X , with an arrow between x and x' if $x \sim x'$.

Examples

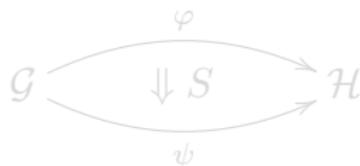
- A group G is a groupoid with one object, and whose arrows are exactly G .
- A set X can be perceived as a **trivial groupoid** whose objects are the points of X and arrows are exactly the corresponding units.
- Given a set X , the **pair groupoid** is the groupoid whose objects are points of X and arrows are all pairs (x, x') in $X \times X$.
- Given an equivalence relation \sim on a set X , the **relation groupoid** R has objects points of X , with an arrow between x and x' if $x \sim x'$.

Examples

- A group G is a groupoid with one object, and whose arrows are exactly G .
- A set X can be perceived as a **trivial groupoid** whose objects are the points of X and arrows are exactly the corresponding units.
- Given a set X , the **pair groupoid** is the groupoid whose objects are points of X and arrows are all pairs (x, x') in $X \times X$.
- Given an equivalence relation \sim on a set X , the **relation groupoid** R has objects points of X , with an arrow between x and x' if $x \sim x'$.

Definition

A morphism/arrow/1-cell of groupoids is a functor, and a 2-morphism/2-arrow/2-cell is a natural transformation.



- Groupoids, functors, and natural transformations form a (strict) 2-category.

Definition

A morphism/arrow/1-cell of groupoids is a functor, and a 2-morphism/2-arrow/2-cell is a natural transformation.

$$\begin{array}{ccc} & \varphi & \\ \mathcal{G} & \begin{array}{c} \curvearrowright \\ \Downarrow S \\ \curvearrowleft \end{array} & \mathcal{H} \\ & \psi & \end{array}$$

- Groupoids, functors, and natural transformations form a (strict) 2-category.

Definition

A morphism/arrow/1-cell of groupoids is a functor, and a 2-morphism/2-arrow/2-cell is a natural transformation.

$$\begin{array}{ccc} & \varphi & \\ \mathcal{G} & \begin{array}{c} \curvearrowright \\ \Downarrow S \\ \curvearrowleft \end{array} & \mathcal{H} \\ & \psi & \end{array}$$

- Groupoids, functors, and natural transformations form a (strict) 2-category.

Definition

A morphism/arrow/1-cell of groupoids is a functor, and a 2-morphism/2-arrow/2-cell is a natural transformation.

$$\begin{array}{ccc} & \varphi & \\ \mathcal{G} & \begin{array}{c} \curvearrowright \\ \Downarrow S \\ \curvearrowleft \end{array} & \mathcal{H} \\ & \psi & \end{array}$$

- Groupoids, functors, and natural transformations form a (strict) 2-category.

Definition

A **Lie groupoid** is a groupoid in which the object and arrow sets are smooth manifolds, and all structure maps are smooth. Additionally, we require s and t to be surjective submersions (*i.e.* local subductions). (For the purposes of this talk, we also require arrow spaces to be Hausdorff.)

Definition

A functor $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if $\varphi_0: \mathcal{G}_0 \rightarrow \mathcal{H}_0$ and $\varphi_1: \mathcal{G}_1 \rightarrow \mathcal{H}_1$ are smooth. A natural transformation $S: \varphi \Rightarrow \psi$ between two smooth functors $\varphi, \psi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if the corresponding map $\mathcal{G}_0 \rightarrow \mathcal{H}_1$ is smooth.

- Lie groupoids, smooth functors, and smooth natural transformations form a 2-category, denoted **LieGpoid**.

Definition

A **Lie groupoid** is a groupoid in which the object and arrow sets are smooth manifolds, and all structure maps are smooth. Additionally, we require s and t to be surjective submersions (*i.e.* local subductions). (For the purposes of this talk, we also require arrow spaces to be Hausdorff.)

Definition

A functor $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if $\varphi_0: \mathcal{G}_0 \rightarrow \mathcal{H}_0$ and $\varphi_1: \mathcal{G}_1 \rightarrow \mathcal{H}_1$ are smooth. A natural transformation $S: \varphi \Rightarrow \psi$ between two smooth functors $\varphi, \psi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if the corresponding map $\mathcal{G}_0 \rightarrow \mathcal{H}_1$ is smooth.

- Lie groupoids, smooth functors, and smooth natural transformations form a 2-category, denoted **LieGpoid**.

Definition

A **Lie groupoid** is a groupoid in which the object and arrow sets are smooth manifolds, and all structure maps are smooth. Additionally, we require s and t to be surjective submersions (*i.e.* local subductions). (For the purposes of this talk, we also require arrow spaces to be Hausdorff.)

Definition

A functor $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if $\varphi_0: \mathcal{G}_0 \rightarrow \mathcal{H}_0$ and $\varphi_1: \mathcal{G}_1 \rightarrow \mathcal{H}_1$ are smooth. A natural transformation $S: \varphi \Rightarrow \psi$ between two smooth functors $\varphi, \psi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if the corresponding map $\mathcal{G}_0 \rightarrow \mathcal{H}_1$ is smooth.

- Lie groupoids, smooth functors, and smooth natural transformations form a 2-category, denoted **LieGpoid**.

Definition

A **Lie groupoid** is a groupoid in which the object and arrow sets are smooth manifolds, and all structure maps are smooth. Additionally, we require s and t to be surjective submersions (*i.e.* local subductions). (For the purposes of this talk, we also require arrow spaces to be Hausdorff.)

Definition

A functor $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if $\varphi_0: \mathcal{G}_0 \rightarrow \mathcal{H}_0$ and $\varphi_1: \mathcal{G}_1 \rightarrow \mathcal{H}_1$ are smooth. A natural transformation $S: \varphi \Rightarrow \psi$ between two smooth functors $\varphi, \psi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if the corresponding map $\mathcal{G}_0 \rightarrow \mathcal{H}_1$ is smooth.

- Lie groupoids, smooth functors, and smooth natural transformations form a 2-category, denoted **LieGpoid**.

Definition

A **Lie groupoid** is a groupoid in which the object and arrow sets are smooth manifolds, and all structure maps are smooth. Additionally, we require s and t to be surjective submersions (*i.e.* local subductions). (For the purposes of this talk, we also require arrow spaces to be Hausdorff.)

Definition

A functor $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if $\varphi_0: \mathcal{G}_0 \rightarrow \mathcal{H}_0$ and $\varphi_1: \mathcal{G}_1 \rightarrow \mathcal{H}_1$ are smooth. A natural transformation $S: \varphi \Rightarrow \psi$ between two smooth functors $\varphi, \psi: \mathcal{G} \rightarrow \mathcal{H}$ is **smooth** if the corresponding map $\mathcal{G}_0 \rightarrow \mathcal{H}_1$ is smooth.

- Lie groupoids, smooth functors, and smooth natural transformations form a 2-category, denoted **LieGpoid**.

Example

- A Lie group is a Lie groupoid.
- A manifold is a Lie groupoid.
- Given a Lie group G acting on a manifold M , the **action groupoid** $G \ltimes M$ is a Lie groupoid whose objects are points of M and arrows are pairs (g, x) in $G \times M$. The source map sends (g, x) to x , and the target sends (g, x) to $g \cdot x$.
- Given a vector field on a manifold M , its local flow induces a Lie groupoid whose object space is M and arrow space is a submanifold of $\mathbb{R} \times M$.

Example

- A Lie group is a Lie groupoid.
- A manifold is a Lie groupoid.
- Given a Lie group G acting on a manifold M , the **action groupoid** $G \ltimes M$ is a Lie groupoid whose objects are points of M and arrows are pairs (g, x) in $G \times M$. The source map sends (g, x) to x , and the target sends (g, x) to $g \cdot x$.
- Given a vector field on a manifold M , its local flow induces a Lie groupoid whose object space is M and arrow space is a submanifold of $\mathbb{R} \times M$.

Example

- A Lie group is a Lie groupoid.
- A manifold is a Lie groupoid.
- Given a Lie group G acting on a manifold M , the **action groupoid** $G \ltimes M$ is a Lie groupoid whose objects are points of M and arrows are pairs (g, x) in $G \times M$. The source map sends (g, x) to x , and the target sends (g, x) to $g \cdot x$.
- Given a vector field on a manifold M , its local flow induces a Lie groupoid whose object space is M and arrow space is a submanifold of $\mathbb{R} \times M$.

Example

- A Lie group is a Lie groupoid.
- A manifold is a Lie groupoid.
- Given a Lie group G acting on a manifold M , the **action groupoid** $G \ltimes M$ is a Lie groupoid whose objects are points of M and arrows are pairs (g, x) in $G \times M$. The source map sends (g, x) to x , and the target sends (g, x) to $g \cdot x$.
- Given a vector field on a manifold M , its local flow induces a Lie groupoid whose object space is M and arrow space is a submanifold of $\mathbb{R} \times M$.

Example

- A Lie group is a Lie groupoid.
- A manifold is a Lie groupoid.
- Given a Lie group G acting on a manifold M , the **action groupoid** $G \ltimes M$ is a Lie groupoid whose objects are points of M and arrows are pairs (g, x) in $G \times M$. The source map sends (g, x) to x , and the target sends (g, x) to $g \cdot x$.
- Given a vector field on a manifold M , its local flow induces a Lie groupoid whose object space is M and arrow space is a submanifold of $\mathbb{R} \times M$.

Definition

A **diffeological groupoid** is a groupoid $\mathcal{G} = (\mathcal{G}_1 \rightrightarrows \mathcal{G}_0)$ in which \mathcal{G}_1 and \mathcal{G}_0 are diffeological spaces, and all structure maps are diffeologically smooth.

- The source and target maps are automatically subductions, but unlike the Lie category, *they are not local subductions*.
- Smooth functors and smooth natural transformations are defined analogously to the Lie case, which gives us a strict 2-category, \mathbf{DGpoid} .
- \mathbf{DGpoid} contains Lie groupoids, relation groupoids, inertia groupoids, integrations of Lie algebroids, etc.

Definition

A **diffeological groupoid** is a groupoid $\mathcal{G} = (\mathcal{G}_1 \rightrightarrows \mathcal{G}_0)$ in which \mathcal{G}_1 and \mathcal{G}_0 are diffeological spaces, and all structure maps are diffeologically smooth.

- The source and target maps are automatically subductions, but unlike the Lie category, *they are not local subductions*.
- Smooth functors and smooth natural transformations are defined analogously to the Lie case, which gives us a strict 2-category, \mathbf{DGpoid} .
- \mathbf{DGpoid} contains Lie groupoids, relation groupoids, inertia groupoids, integrations of Lie algebroids, etc.

Definition

A **diffeological groupoid** is a groupoid $\mathcal{G} = (\mathcal{G}_1 \rightrightarrows \mathcal{G}_0)$ in which \mathcal{G}_1 and \mathcal{G}_0 are diffeological spaces, and all structure maps are diffeologically smooth.

- The source and target maps are automatically subductions, but unlike the Lie category, *they are not local subductions*.
- Smooth functors and smooth natural transformations are defined analogously to the Lie case, which gives us a strict 2-category, **DGpoid**.
- **DGpoid** contains Lie groupoids, relation groupoids, inertia groupoids, integrations of Lie algebroids, etc.

Definition

A **diffeological groupoid** is a groupoid $\mathcal{G} = (\mathcal{G}_1 \rightrightarrows \mathcal{G}_0)$ in which \mathcal{G}_1 and \mathcal{G}_0 are diffeological spaces, and all structure maps are diffeologically smooth.

- The source and target maps are automatically subductions, but unlike the Lie category, *they are not local subductions*.
- Smooth functors and smooth natural transformations are defined analogously to the Lie case, which gives us a strict 2-category, **DGpoid**.
- **DGpoid** contains Lie groupoids, relation groupoids, inertia groupoids, integrations of Lie algebroids, etc.

Equivalences of Categories

- In mathematics, we love equivalences of categories:
 - $\mathbb{N} \leftrightarrow \mathbf{FiniteSets}$ is an equivalence of categories.
 - The category of covering spaces of a (nice) path-connected topological space X forms a category equivalent to the category of permutation representations of $\pi_1(X)$.
- So what is an equivalence of categories?

Equivalences of Categories

- In mathematics, we love equivalences of categories:
 - $\mathbb{N} \leftrightarrow \mathbf{FiniteSets}$ is an equivalence of categories.
 - The category of covering spaces of a (nice) path-connected topological space X forms a category equivalent to the category of permutation representations of $\pi_1(X)$.
- So what is an equivalence of categories?

Equivalences of Categories

- In mathematics, we love equivalences of categories:
 - $\mathbb{N} \leftrightarrow \mathbf{FiniteSets}$ is an equivalence of categories.
 - The category of covering spaces of a (nice) path-connected topological space X forms a category equivalent to the category of permutation representations of $\pi_1(X)$.
- So what is an equivalence of categories?

Equivalences of Categories

- In mathematics, we love equivalences of categories:
 - $\mathbb{N} \leftrightarrow \mathbf{FiniteSets}$ is an equivalence of categories.
 - The category of covering spaces of a (nice) path-connected topological space X forms a category equivalent to the category of permutation representations of $\pi_1(X)$.
- So what is an equivalence of categories?

Equivalence of Categories

Definition

Given categories \mathcal{C} and \mathcal{D} , an equivalence of categories $f: \mathcal{C} \rightarrow \mathcal{D}$ is a functor equipped with another functor $g: \mathcal{D} \rightarrow \mathcal{C}$ and two natural transformations $S: \text{id}_{\mathcal{C}} \Rightarrow g \circ f$ and $T: f \circ g \Rightarrow \text{id}_{\mathcal{D}}$. Sometimes, these are also required to satisfying the Triangle Identities:

$$(Tf) \circ (fS) = \text{id}_{\varphi} \quad \text{and} \quad (gT) \circ (Sg) = \text{id}_{\psi}.$$

Example

Suppose $\rho: P \rightarrow M$ is a principal G -bundle. If the action groupoid $G \ltimes P$ admits an equivalence to the groupoid M , then P must be the trivial bundle.

Equivalence of Categories

Definition

Given categories \mathcal{C} and \mathcal{D} , an equivalence of categories $f: \mathcal{C} \rightarrow \mathcal{D}$ is a functor equipped with another functor $g: \mathcal{D} \rightarrow \mathcal{C}$ and two natural transformations $S: \text{id}_{\mathcal{C}} \Rightarrow g \circ f$ and $T: f \circ g \Rightarrow \text{id}_{\mathcal{D}}$. Sometimes, these are also required to satisfying the Triangle Identities:

$$(Tf) \circ (fS) = \text{id}_{\varphi} \quad \text{and} \quad (gT) \circ (Sg) = \text{id}_{\psi}.$$

Example

Suppose $\rho: P \rightarrow M$ is a principal G -bundle. If the action groupoid $G \ltimes P$ admits an equivalence to the groupoid M , then P must be the trivial bundle.

Equivalence of Categories

Definition

Given categories \mathcal{C} and \mathcal{D} , an equivalence of categories $f: \mathcal{C} \rightarrow \mathcal{D}$ is a functor equipped with another functor $g: \mathcal{D} \rightarrow \mathcal{C}$ and two natural transformations $S: \text{id}_{\mathcal{C}} \Rightarrow g \circ f$ and $T: f \circ g \Rightarrow \text{id}_{\mathcal{D}}$. Sometimes, these are also required to satisfying the Triangle Identities:

$$(Tf) \circ (fS) = \text{id}_{\varphi} \quad \text{and} \quad (gT) \circ (Sg) = \text{id}_{\psi}.$$

Example

Suppose $\rho: P \rightarrow M$ is a principal G -bundle. If the action groupoid $G \ltimes P$ admits an equivalence to the groupoid M , then P must be the trivial bundle.

Equivalence of Categories

Definition

Given categories \mathcal{C} and \mathcal{D} , an equivalence of categories $f: \mathcal{C} \rightarrow \mathcal{D}$ is a functor equipped with another functor $g: \mathcal{D} \rightarrow \mathcal{C}$ and two natural transformations $S: \text{id}_{\mathcal{C}} \Rightarrow g \circ f$ and $T: f \circ g \Rightarrow \text{id}_{\mathcal{D}}$. Sometimes, these are also required to satisfying the Triangle Identities:

$$(Tf) \circ (fS) = \text{id}_{\varphi} \quad \text{and} \quad (gT) \circ (Sg) = \text{id}_{\psi}.$$

Example

Suppose $\rho: P \rightarrow M$ is a principal G -bundle. If the action groupoid $G \ltimes P$ admits an equivalence to the groupoid M , then P must be the trivial bundle.

Equivalence of Categories

- It turns out this notion of equivalence is too strong!
- A solution is to consider an “equivalent definition of equivalence” in the case of small categories: we can ask for the functor to be **essentially surjective** on objects (*i.e.* surjective up to isomorphism), and **fully faithful** (*i.e.* bijective on hom sets). With this in mind...

Equivalence of Categories

- It turns out this notion of equivalence is too strong!
- A solution is to consider an “equivalent definition of equivalence” in the case of small categories: we can ask for the functor to be **essentially surjective** on objects (*i.e.* surjective up to isomorphism), and **fully faithful** (*i.e.* bijective on hom sets). With this in mind...

Equivalence of Categories

- It turns out this notion of equivalence is too strong!
- A solution is to consider an “equivalent definition of equivalence” in the case of small categories: we can ask for the functor to be **essentially surjective** on objects (*i.e.* surjective up to isomorphism), and **fully faithful** (*i.e.* bijective on hom sets). With this in mind...

Equivalence of Categories

- It turns out this notion of equivalence is too strong!
- A solution is to consider an “equivalent definition of equivalence” in the case of small categories: we can ask for the functor to be **essentially surjective** on objects (*i.e.* surjective up to isomorphism), and **fully faithful** (*i.e.* bijective on hom sets). With this in mind...

Definition

A **weak equivalence** $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ in \mathbf{DGPoid} is a smooth functor that satisfies

① **(Smooth Essential Surjectivity)**

$\Psi_\varphi: \mathcal{G}_{0,\varphi} \times_t \mathcal{H}_1 \rightarrow \mathcal{H}_0: (x, h) \mapsto s(h)$ is a *subduction*,

② **(Smooth Fully Faithfulness)**

$\Phi_\varphi: \mathcal{G}_1 \rightarrow (\mathcal{G}_0^2)_{\varphi^2 \times (s,t)} \mathcal{H}_1: g \mapsto (s(g), t(g), \varphi(g))$ is a diffeomorphism.

- A smoothly fully faithful functor that is subductive on objects is automatically a weak equivalence, called a **subductive weak equivalence**.

Definition

A **weak equivalence** $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ in \mathbf{DGPoid} is a smooth functor that satisfies

① **(Smooth Essential Surjectivity)**

$\Psi_\varphi: \mathcal{G}_{0,\varphi} \times_t \mathcal{H}_1 \rightarrow \mathcal{H}_0: (x, h) \mapsto s(h)$ is a *subduction*,

② **(Smooth Fully Faithfulness)**

$\Phi_\varphi: \mathcal{G}_1 \rightarrow (\mathcal{G}_0^2)_{\varphi^2 \times (s,t)} \mathcal{H}_1: g \mapsto (s(g), t(g), \varphi(g))$ is a diffeomorphism.

- A smoothly fully faithful functor that is subductive on objects is automatically a weak equivalence, called a **subductive weak equivalence**.

Definition

A **weak equivalence** $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ in \mathbf{DGPoid} is a smooth functor that satisfies

1 **(Smooth Essential Surjectivity)**

$\Psi_\varphi: \mathcal{G}_{0,\varphi} \times_t \mathcal{H}_1 \rightarrow \mathcal{H}_0: (x, h) \mapsto s(h)$ is a *subduction*,

2 **(Smooth Fully Faithfulness)**

$\Phi_\varphi: \mathcal{G}_1 \rightarrow (\mathcal{G}_0^2)_{\varphi^2 \times_{(s,t)}} \mathcal{H}_1: g \mapsto (s(g), t(g), \varphi(g))$ is a diffeomorphism.

- A smoothly fully faithful functor that is subductive on objects is automatically a weak equivalence, called a **subductive weak equivalence**.

Definition

A **weak equivalence** $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ in \mathbf{DGPoid} is a smooth functor that satisfies

1 **(Smooth Essential Surjectivity)**

$\Psi_\varphi: \mathcal{G}_{0,\varphi} \times_t \mathcal{H}_1 \rightarrow \mathcal{H}_0: (x, h) \mapsto s(h)$ is a *subduction*,

2 **(Smooth Fully Faithfulness)**

$\Phi_\varphi: \mathcal{G}_1 \rightarrow (\mathcal{G}_0^2)_{\varphi^2 \times (s,t)} \mathcal{H}_1: g \mapsto (s(g), t(g), \varphi(g))$ is a diffeomorphism.

- A smoothly fully faithful functor that is subductive on objects is automatically a weak equivalence, called a **subductive weak equivalence**.

Weak Equivalences

Example

The action groupoid of any principal G -bundle over a manifold M is weakly equivalent to M .

- The problem with weak equivalences is that they are not necessarily invertible!

Example

The weak equivalences in the previous example are invertible if and only if the bundle is trivial.

- **Goal:** formally invert weak equivalences by extending $DG\text{poid}$ to include “pseudo-inverses” of them.

Weak Equivalences

Example

The action groupoid of any principal G -bundle over a manifold M is weakly equivalent to M .

- The problem with weak equivalences is that they are not necessarily invertible!

Example

The weak equivalences in the previous example are invertible if and only if the bundle is trivial.

- **Goal:** formally invert weak equivalences by extending \mathbf{DGpoid} to include “pseudo-inverses” of them.

Weak Equivalences

Example

The action groupoid of any principal G -bundle over a manifold M is weakly equivalent to M .

- The problem with weak equivalences is that they are not necessarily invertible!

Example

The weak equivalences in the previous example are invertible if and only if the bundle is trivial.

- **Goal:** formally invert weak equivalences by extending DGpoid to include “pseudo-inverses” of them.

Example

The action groupoid of any principal G -bundle over a manifold M is weakly equivalent to M .

- The problem with weak equivalences is that they are not necessarily invertible!

Example

The weak equivalences in the previous example are invertible if and only if the bundle is trivial.

- **Goal:** formally invert weak equivalences by extending \mathbf{DGpoid} to include “pseudo-inverses” of them.

Bicategory of Fractions

- Let W be the class of all weak equivalences between diffeological groupoids.
- Define a bicategory $\mathbf{DG}_{\text{poid}}[W^{-1}]$, the **bicategory of fractions**, as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is a **generalised morphism**:



- A generalised morphism is a **Morita equivalence** if both functors are weak equivalences.

Bicategory of Fractions

- Let W be the class of all weak equivalences between diffeological groupoids.
- Define a bicategory $\mathbf{DG}_{\text{poid}}[W^{-1}]$, the **bicategory of fractions**, as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is a **generalised morphism**:



- A generalised morphism is a **Morita equivalence** if both functors are weak equivalences.

Bicategory of Fractions

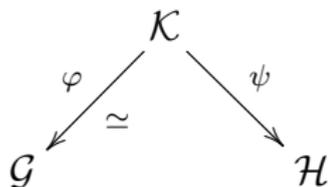
- Let W be the class of all weak equivalences between diffeological groupoids.
- Define a bicategory $\mathbf{DG}_{\text{poid}}[W^{-1}]$, the **bicategory of fractions**, as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is a **generalised morphism**:



- A generalised morphism is a **Morita equivalence** if both functors are weak equivalences.

Bicategory of Fractions

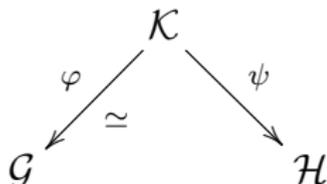
- Let W be the class of all weak equivalences between diffeological groupoids.
- Define a bicategory $\mathbf{DG}_{\text{poid}}[W^{-1}]$, the **bicategory of fractions**, as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is a **generalised morphism**:



- A generalised morphism is a **Morita equivalence** if both functors are weak equivalences.

Bicategory of Fractions

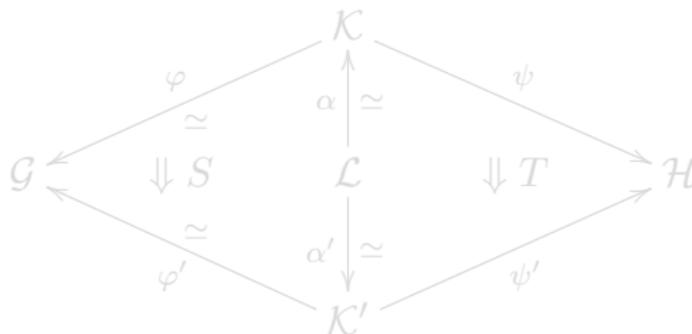
- Let W be the class of all weak equivalences between diffeological groupoids.
- Define a bicategory $\mathbf{DG}_{\text{poid}}[W^{-1}]$, the **bicategory of fractions**, as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is a **generalised morphism**:



- A generalised morphism is a **Morita equivalence** if both functors are weak equivalences.

Bicategory of Fractions

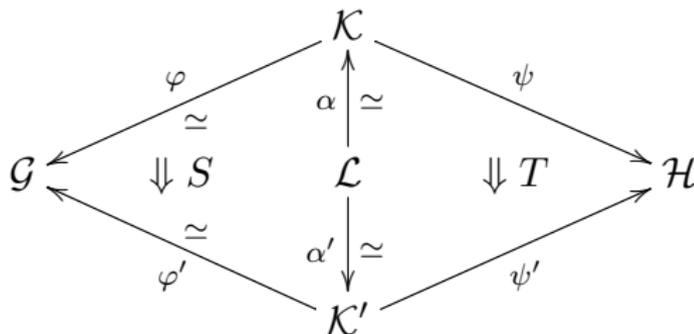
- 2 A 2-cell between two generalised morphisms is an equivalence class of 2-commutative diagrams



- The equivalence relation is given by yet another generalised morphism between the centres of the diagrams, and some identities involving the natural transformations. (See Pronk [P96] or [W] for details.)

Bicategory of Fractions

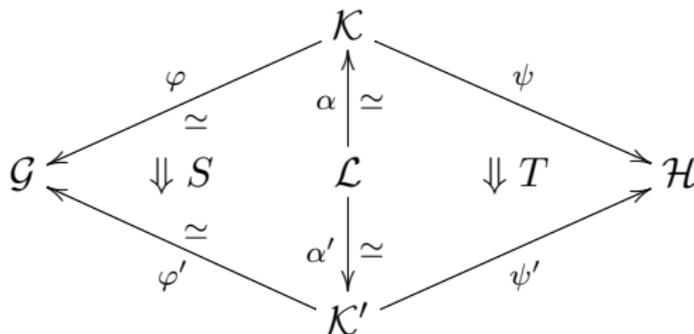
- 2 A 2-cell between two generalised morphisms is an equivalence class of 2-commutative diagrams



- The equivalence relation is given by yet another generalised morphism between the centres of the diagrams, and some identities involving the natural transformations. (See Pronk [P96] or [W] for details.)

Bicategory of Fractions

- 2 A 2-cell between two generalised morphisms is an equivalence class of 2-commutative diagrams



- The equivalence relation is given by yet another generalised morphism between the centres of the diagrams, and some identities involving the natural transformations. (See Pronk [P96] or [W] for details.)

Example: Open Covers

Example

- Let M be a manifold.
- Let $\{U_\alpha\}$ and $\{V_\beta\}$ be two open covers of M . Define

$$\mathcal{U}_0 := \coprod U_\alpha,$$

$$\mathcal{V}_0 := \coprod V_\beta.$$

- Let

$$\mathcal{U}_1 := \coprod U_\alpha \cap U_{\alpha'},$$

$$\mathcal{V}_1 := \coprod V_\beta \cap V_{\beta'}.$$

- \mathcal{U} and \mathcal{V} are so-called Čech groupoids of M .

Example: Open Covers

Example

- Let M be a manifold.
- Let $\{U_\alpha\}$ and $\{V_\beta\}$ be two open covers of M . Define

$$\mathcal{U}_0 := \coprod U_\alpha,$$

$$\mathcal{V}_0 := \coprod V_\beta.$$

- Let

$$\mathcal{U}_1 := \coprod U_\alpha \cap U_{\alpha'},$$

$$\mathcal{V}_1 := \coprod V_\beta \cap V_{\beta'}.$$

- \mathcal{U} and \mathcal{V} are so-called Čech groupoids of M .

Example: Open Covers

Example

- Let M be a manifold.
- Let $\{U_\alpha\}$ and $\{V_\beta\}$ be two open covers of M . Define

$$\mathcal{U}_0 := \coprod U_\alpha,$$

$$\mathcal{V}_0 := \coprod V_\beta.$$

- Let

$$\mathcal{U}_1 := \coprod U_\alpha \cap U_{\alpha'},$$

$$\mathcal{V}_1 := \coprod V_\beta \cap V_{\beta'}.$$

- \mathcal{U} and \mathcal{V} are so-called Čech groupoids of M .

Example: Open Covers

Example

- Let M be a manifold.
- Let $\{U_\alpha\}$ and $\{V_\beta\}$ be two open covers of M . Define

$$\mathcal{U}_0 := \coprod U_\alpha,$$

$$\mathcal{V}_0 := \coprod V_\beta.$$

- Let

$$\mathcal{U}_1 := \coprod U_\alpha \cap U_{\alpha'},$$

$$\mathcal{V}_1 := \coprod V_\beta \cap V_{\beta'}.$$

- \mathcal{U} and \mathcal{V} are so-called Čech groupoids of M .

Example: Open Covers

Example

- Let M be a manifold.
- Let $\{U_\alpha\}$ and $\{V_\beta\}$ be two open covers of M . Define

$$\mathcal{U}_0 := \coprod U_\alpha,$$

$$\mathcal{V}_0 := \coprod V_\beta.$$

- Let

$$\mathcal{U}_1 := \coprod U_\alpha \cap U_{\alpha'},$$

$$\mathcal{V}_1 := \coprod V_\beta \cap V_{\beta'}.$$

- \mathcal{U} and \mathcal{V} are so-called Čech groupoids of M .

Example: Open Covers

Example

- If $\{W_\gamma\}$ is a refinement of the two open covers, then we construct a Čech groupoid \mathcal{W} similarly.
- We have the generalised morphism

$$\begin{array}{ccc} & \mathcal{W} & \\ \cong \swarrow & & \searrow \cong \\ \mathcal{U} & & \mathcal{V} \end{array}$$

where the two functors are inclusions.

Example: Open Covers

Example

- If $\{W_\gamma\}$ is a refinement of the two open covers, then we construct a Čech groupoid \mathcal{W} similarly.
- We have the generalised morphism

$$\begin{array}{ccc} & \mathcal{W} & \\ \cong \swarrow & & \searrow \cong \\ \mathcal{U} & & \mathcal{V} \end{array}$$

where the two functors are inclusions.

Example: Open Covers

Example

- If $\{W_\gamma\}$ is a refinement of the two open covers, then we construct a Čech groupoid \mathcal{W} similarly.
- We have the generalised morphism

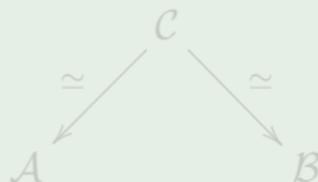
$$\begin{array}{ccc} & \mathcal{W} & \\ \cong \swarrow & & \searrow \cong \\ \mathcal{U} & & \mathcal{V} \end{array}$$

where the two functors are inclusions.

Example: Effective Orbifold

Example

- Through the work of Moerdijk and Pronk [MP97], we can do a similar procedure with orbifolds atlases:
- Two orbifold atlases (viewed as Lie groupoids) \mathcal{A} and \mathcal{B} are equivalent if their charts are all compatible, leading to a larger orbifold atlas.
- More precisely, if there is another orbifold atlas \mathcal{C} and a Morita equivalence



then the orbifold atlases are equivalent; they describe the same orbifold.

Example: Effective Orbifold

Example

- Through the work of Moerdijk and Pronk [MP97], we can do a similar procedure with orbifolds atlases:
- Two orbifold atlases (viewed as Lie groupoids) \mathcal{A} and \mathcal{B} are equivalent if their charts are all compatible, leading to a larger orbifold atlas.
- More precisely, if there is another orbifold atlas \mathcal{C} and a Morita equivalence

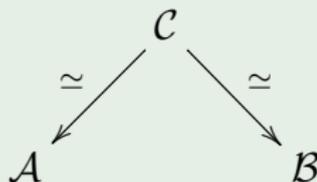


then the orbifold atlases are equivalent; they describe the same orbifold.

Example: Effective Orbifold

Example

- Through the work of Moerdijk and Pronk [MP97], we can do a similar procedure with orbifolds atlases:
- Two orbifold atlases (viewed as Lie groupoids) \mathcal{A} and \mathcal{B} are equivalent if their charts are all compatible, leading to a larger orbifold atlas.
- More precisely, if there is another orbifold atlas \mathcal{C} and a Morita equivalence

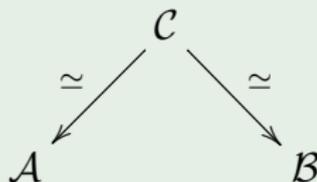


then the orbifold atlases are equivalent; they describe the same orbifold.

Example: Effective Orbifold

Example

- Through the work of Moerdijk and Pronk [MP97], we can do a similar procedure with orbifolds atlases:
- Two orbifold atlases (viewed as Lie groupoids) \mathcal{A} and \mathcal{B} are equivalent if their charts are all compatible, leading to a larger orbifold atlas.
- More precisely, if there is another orbifold atlas \mathcal{C} and a Morita equivalence



then the orbifold atlases are equivalent; they describe the same orbifold.

Example: Spanisation

Example

- Let $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ be a functor. There is a corresponding generalised morphism:

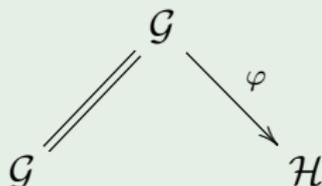


called the **spanisation** of φ .

Example: Spanisation

Example

- Let $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ be a functor. There is a corresponding generalised morphism:

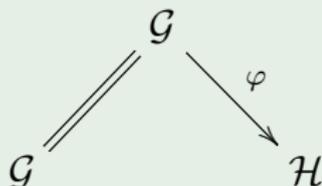


called the **spanisation** of φ .

Example: Spanisation

Example

- Let $\varphi: \mathcal{G} \rightarrow \mathcal{H}$ be a functor. There is a corresponding generalised morphism:

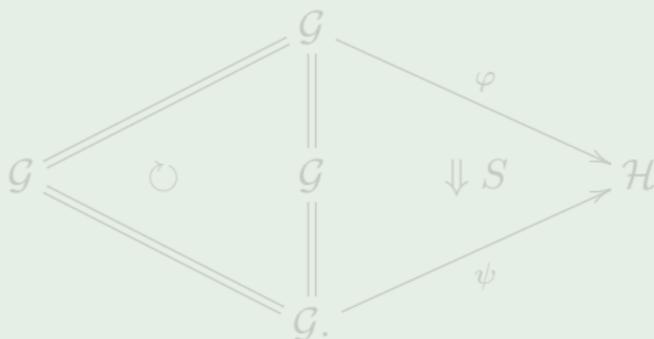


called the **spanisation** of φ .

Example: Spanisation

Example

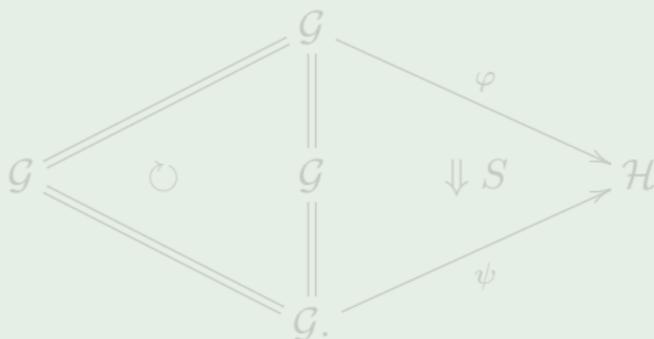
- Let $\psi: \mathcal{G} \rightarrow \mathcal{H}$ be another functor, and $S: \varphi \Rightarrow \psi$ a natural transformation.
- The **spanisation** of S is given by the 2-cell represented by the diagram



Example: Spanisation

Example

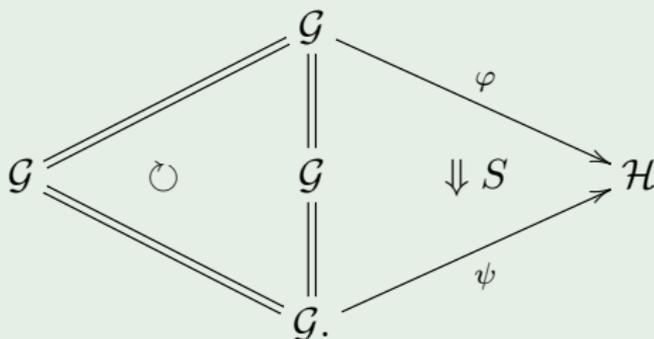
- Let $\psi: \mathcal{G} \rightarrow \mathcal{H}$ be another functor, and $S: \varphi \Rightarrow \psi$ a natural transformation.
- The **spanisation** of S is given by the 2-cell represented by the diagram



Example: Spanisation

Example

- Let $\psi: \mathcal{G} \rightarrow \mathcal{H}$ be another functor, and $S: \varphi \Rightarrow \psi$ a natural transformation.
- The **spanisation** of S is given by the 2-cell represented by the diagram



Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are generalised morphisms, and 2-cells are as described above, denoted $\mathbf{DGpoid}[W^{-1}]$, admits an inclusion pseudofunctor $\mathfrak{S}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}[W^{-1}]$ given by spanisation, and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- The following generalised morphisms are pseudo-inverses of each other:

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ \mathcal{G} & \simeq & \mathcal{H} \end{array} \qquad \begin{array}{ccc} & \mathcal{K} & \\ \psi \swarrow & & \searrow \varphi \\ \mathcal{H} & \simeq & \mathcal{G} \end{array}$$

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are generalised morphisms, and 2-cells are as described above, denoted $\mathbf{DGpoid}[W^{-1}]$, admits an inclusion pseudofunctor $\mathfrak{S}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}[W^{-1}]$ given by spanisation, and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- The following generalised morphisms are pseudo-inverses of each other:



Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are generalised morphisms, and 2-cells are as described above, denoted $\mathbf{DGpoid}[W^{-1}]$, admits an inclusion pseudofunctor $\mathfrak{S}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}[W^{-1}]$ given by spanisation, and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- The following generalised morphisms are pseudo-inverses of each other:



Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are generalised morphisms, and 2-cells are as described above, denoted $\mathbf{DGpoid}[W^{-1}]$, admits an inclusion pseudofunctor $\mathfrak{S}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}[W^{-1}]$ given by spanisation, and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- The following generalised morphisms are pseudo-inverses of each other:

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ \mathcal{G} & \simeq & \mathcal{H} \end{array} \qquad \begin{array}{ccc} & \mathcal{K} & \\ \psi \swarrow & & \searrow \varphi \\ \mathcal{H} & \simeq & \mathcal{G} \end{array}$$

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are generalised morphisms, and 2-cells are as described above, denoted $\mathbf{DGpoid}[W^{-1}]$, admits an inclusion pseudofunctor $\mathfrak{S}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}[W^{-1}]$ given by spanisation, and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- The following generalised morphisms are pseudo-inverses of each other:

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ \mathcal{G} & \simeq & \mathcal{H} \end{array} \qquad \begin{array}{ccc} & \mathcal{K} & \\ \psi \swarrow & & \searrow \varphi \\ \mathcal{H} & \simeq & \mathcal{G}. \end{array}$$

Anafunctors

- While the bicategory of fractions is very natural, working with 2-cells can be very tedious.
- Define a bicategory $\mathbf{DG}_{\text{poid}}^{\text{ana}}$, the **anafunctor bicategory**, à la Roberts [R21] as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is an **anafunctor**:



- The double arrow indicates that this is subductive on objects.

Anafunctors

- While the bicategory of fractions is very natural, working with 2-cells can be very tedious.
- Define a bicategory $\mathbf{DG}_{\text{poid}}^{\text{ana}}$, the **anafunctor bicategory**, à la Roberts [R21] as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is an **anafunctor**:



- The double arrow indicates that this is subductive on objects.

Anafunctors

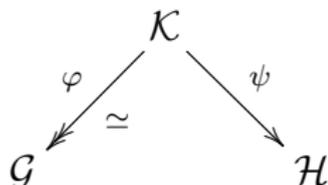
- While the bicategory of fractions is very natural, working with 2-cells can be very tedious.
- Define a bicategory $\mathbf{DG}_{\text{poid}}^{\text{ana}}$, the **anafunctor bicategory**, à la Roberts [R21] as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is an **anafunctor**:



- The double arrow indicates that this is subductive on objects.

Anafunctors

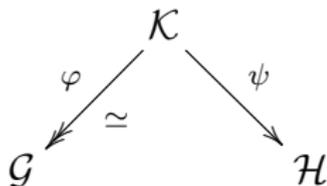
- While the bicategory of fractions is very natural, working with 2-cells can be very tedious.
- Define a bicategory $\mathbf{DG}_{\text{poid}}^{\text{ana}}$, the **anafunctor bicategory**, à la Roberts [R21] as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is an **anafunctor**:



- The double arrow indicates that this is subductive on objects.

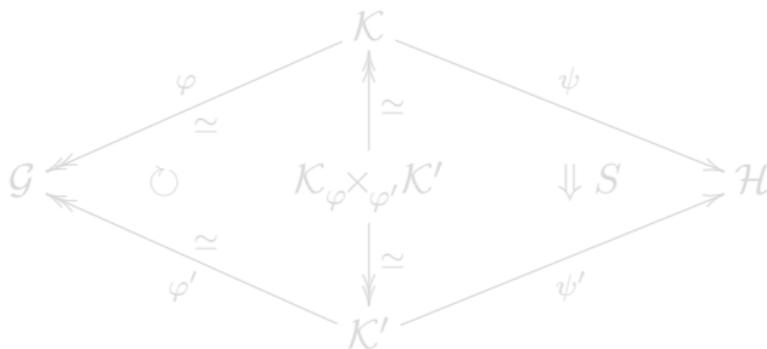
Anafunctors

- While the bicategory of fractions is very natural, working with 2-cells can be very tedious.
- Define a bicategory $\mathbf{DG}_{\text{poid}}^{\text{ana}}$, the **anafunctor bicategory**, à la Roberts [R21] as follows:
 - 0 Objects are diffeological groupoids.
 - 1 A 1-cell from \mathcal{G} to \mathcal{H} is an **anafunctor**:

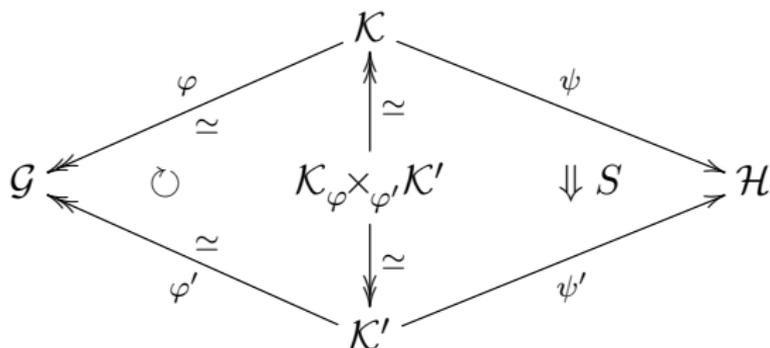


- The double arrow indicates that this is subductive on objects.

- 2 A 2-cell between two anafunctors is a 2-commutative diagram called a **transformation**:



- 2 A 2-cell between two anafunctors is a 2-commutative diagram called a **transformation**:



Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are anafunctors, and 2-cells are transformations, denoted $\mathbf{DGpoid}_{\text{ana}}$, admits an inclusion functor $\mathfrak{A}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}_{\text{ana}}$ (called “anafunctisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

Moreover, there is an equivalence of bicategories $\mathbf{DGpoid}_{\text{ana}} \rightarrow \mathbf{DGpoid}[W^{-1}]$ such that the following triangle 2-commutes

$$\begin{array}{ccc}
 \mathbf{DGpoid}_{\text{ana}} & \xrightarrow{\quad \simeq \quad} & \mathbf{DGpoid}[W^{-1}] \\
 & \swarrow \mathfrak{A} \quad \Rightarrow \quad \searrow \mathfrak{G} & \\
 & \mathbf{DGpoid} &
 \end{array}$$

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are anafunctors, and 2-cells are transformations, denoted $\mathbf{DGpoid}_{\text{ana}}$, admits an inclusion functor $\mathfrak{A}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}_{\text{ana}}$ (called “anafunctisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

Moreover, there is an equivalence of bicategories $\mathbf{DGpoid}_{\text{ana}} \rightarrow \mathbf{DGpoid}[W^{-1}]$ such that the following triangle 2-commutes

$$\begin{array}{ccc}
 \mathbf{DGpoid}_{\text{ana}} & \xrightarrow{\quad \simeq \quad} & \mathbf{DGpoid}[W^{-1}] \\
 & \swarrow \mathfrak{A} \quad \Rightarrow \quad \searrow \mathfrak{G} & \\
 & \mathbf{DGpoid} &
 \end{array}$$

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are anafunctors, and 2-cells are transformations, denoted $\mathbf{DGpoid}_{\text{ana}}$, admits an inclusion functor $\mathfrak{A}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}_{\text{ana}}$ (called “anafunctisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

Moreover, there is an equivalence of bicategories $\mathbf{DGpoid}_{\text{ana}} \rightarrow \mathbf{DGpoid}[W^{-1}]$ such that the following triangle 2-commutes

$$\begin{array}{ccc}
 \mathbf{DGpoid}_{\text{ana}} & \xrightarrow{\quad \simeq \quad} & \mathbf{DGpoid}[W^{-1}] \\
 & \swarrow \mathfrak{A} \quad \Rightarrow \quad \searrow \mathfrak{G} & \\
 & \mathbf{DGpoid} &
 \end{array}$$

Theorem

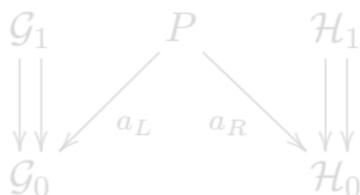
The bicategory whose objects are diffeological groupoids, 1-cells are anafunctors, and 2-cells are transformations, denoted \mathbf{DGpoid}_{ana} , admits an inclusion functor $\mathfrak{A}: \mathbf{DGpoid} \rightarrow \mathbf{DGpoid}_{ana}$ (called “anafunctisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

Moreover, there is an equivalence of bicategories $\mathbf{DGpoid}_{ana} \rightarrow \mathbf{DGpoid}[W^{-1}]$ such that the following triangle 2-commutes

$$\begin{array}{ccc}
 \mathbf{DGpoid}_{ana} & \xrightarrow{\cong} & \mathbf{DGpoid}[W^{-1}] \\
 & \nwarrow \mathfrak{A} \quad \Rightarrow \quad \nearrow \mathfrak{G} & \\
 & \mathbf{DGpoid} &
 \end{array}$$

Definition

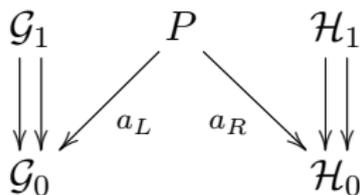
A **right principal bibundle** from \mathcal{G} to \mathcal{H} is a right principal \mathcal{H} -bundle $a_L: P \rightarrow \mathcal{G}_0$ with anchor map $a_R: P \rightarrow \mathcal{H}_0$ equipped with a \mathcal{G} -action with anchor map a_L that commutes with the \mathcal{H} -action, and so that a_R is \mathcal{G} -invariant.



- Here, a_L is only required to be a subduction, not a local subduction.
- If a_R is a left principal \mathcal{G} -bundle as well, then P is a **(diffeological) Morita equivalence**.

Definition

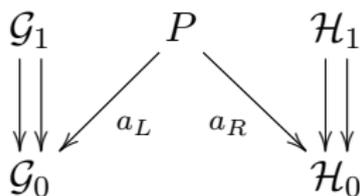
A **right principal bibundle** from \mathcal{G} to \mathcal{H} is a right principal \mathcal{H} -bundle $a_L: P \rightarrow \mathcal{G}_0$ with anchor map $a_R: P \rightarrow \mathcal{H}_0$ equipped with a \mathcal{G} -action with anchor map a_L that commutes with the \mathcal{H} -action, and so that a_R is \mathcal{G} -invariant.



- Here, a_L is only required to be a subduction, not a local subduction.
- If a_R is a left principal \mathcal{G} -bundle as well, then P is a **(diffeological) Morita equivalence**.

Definition

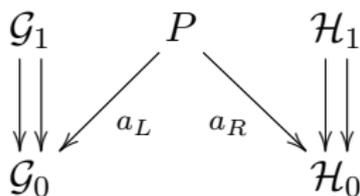
A **right principal bibundle** from \mathcal{G} to \mathcal{H} is a right principal \mathcal{H} -bundle $a_L: P \rightarrow \mathcal{G}_0$ with anchor map $a_R: P \rightarrow \mathcal{H}_0$ equipped with a \mathcal{G} -action with anchor map a_L that commutes with the \mathcal{H} -action, and so that a_R is \mathcal{G} -invariant.



- Here, a_L is only required to be a subduction, not a local subduction.
- If a_R is a left principal \mathcal{G} -bundle as well, then P is a **(diffeological) Morita equivalence**.

Definition

A **right principal bibundle** from \mathcal{G} to \mathcal{H} is a right principal \mathcal{H} -bundle $a_L: P \rightarrow \mathcal{G}_0$ with anchor map $a_R: P \rightarrow \mathcal{H}_0$ equipped with a \mathcal{G} -action with anchor map a_L that commutes with the \mathcal{H} -action, and so that a_R is \mathcal{G} -invariant.



- Here, a_L is only required to be a subduction, not a local subduction.
- If a_R is a left principal \mathcal{G} -bundle as well, then P is a **(diffeological) Morita equivalence**.

- We form a bicategory $\mathbf{DBiBund}$ with 2-cells as follows: given bibundles P and Q between \mathcal{G} and \mathcal{H} , a 2-cell is a $(\mathcal{G}\text{-}\mathcal{H})$ -biequivariant diffeomorphism between P and Q .

Question (Nesta van der Schaaf)

Is a diffeological Morita equivalence between two Lie groupoids the same as a Lie Morita equivalence? [vdS21]

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are right principal bibundles, and 2-cells are bi-equivariant diffeomorphisms, denoted $\mathbf{DBiBund}$, admits an inclusion functor $\mathfrak{B} : \mathbf{DGpoid} \rightarrow \mathbf{DBiBund}$ (called “bibundlisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in \mathcal{W}$.

- We form a bicategory $\mathbf{DBiBund}$ with 2-cells as follows: given bibundles P and Q between \mathcal{G} and \mathcal{H} , a 2-cell is a $(\mathcal{G}\text{-}\mathcal{H})$ -biequivariant diffeomorphism between P and Q .

Question (Nesta van der Schaaf)

Is a diffeological Morita equivalence between two Lie groupoids the same as a Lie Morita equivalence? [vdS21]

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are right principal bibundles, and 2-cells are bi-equivariant diffeomorphisms, denoted $\mathbf{DBiBund}$, admits an inclusion functor $\mathfrak{B} : \mathbf{DGpoid} \rightarrow \mathbf{DBiBund}$ (called “bibundlisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- We form a bicategory $\mathbf{DBiBund}$ with 2-cells as follows: given bibundles P and Q between \mathcal{G} and \mathcal{H} , a 2-cell is a $(\mathcal{G}\text{-}\mathcal{H})$ -biequivariant diffeomorphism between P and Q .

Question (Nesta van der Schaaf)

Is a diffeological Morita equivalence between two Lie groupoids the same as a Lie Morita equivalence? [vdS21]

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are right principal bibundles, and 2-cells are bi-equivariant diffeomorphisms, denoted $\mathbf{DBiBund}$, admits an inclusion functor $\mathfrak{B} : \mathbf{DGpoid} \rightarrow \mathbf{DBiBund}$ (called “bibundlisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- We form a bicategory $\mathbf{DBiBund}$ with 2-cells as follows: given bibundles P and Q between \mathcal{G} and \mathcal{H} , a 2-cell is a $(\mathcal{G}\text{-}\mathcal{H})$ -biequivariant diffeomorphism between P and Q .

Question (Nesta van der Schaaf)

Is a diffeological Morita equivalence between two Lie groupoids the same as a Lie Morita equivalence? [vdS21]

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are right principal bibundles, and 2-cells are bi-equivariant diffeomorphisms, denoted $\mathbf{DBiBund}$, admits an inclusion functor $\mathfrak{B}: \mathbf{DGpoid} \rightarrow \mathbf{DBiBund}$ (called “bibundlisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

- We form a bicategory $\mathbf{DBiBund}$ with 2-cells as follows: given bibundles P and Q between \mathcal{G} and \mathcal{H} , a 2-cell is a $(\mathcal{G}\text{-}\mathcal{H})$ -biequivariant diffeomorphism between P and Q .

Question (Nesta van der Schaaf)

Is a diffeological Morita equivalence between two Lie groupoids the same as a Lie Morita equivalence? [vdS21]

Theorem

The bicategory whose objects are diffeological groupoids, 1-cells are right principal bibundles, and 2-cells are bi-equivariant diffeomorphisms, denoted $\mathbf{DBiBund}$, admits an inclusion functor $\mathfrak{B}: \mathbf{DGpoid} \rightarrow \mathbf{DBiBund}$ (called “bibundlisation”), and admits a pseudo-inverse for every weak equivalence $\varphi \in W$.

Equivalence of Bicategories

Theorem (continued)

Moreover, we have the following 2-commutative diagram

$$\begin{array}{ccccc} \mathrm{DGpoid}[W^{-1}] & \xrightarrow{\simeq} & \mathrm{DGpoid}_{\mathrm{ana}} & \xrightarrow{\simeq} & \mathrm{DBiBund} \\ \uparrow \mathfrak{G} & \searrow \Rightarrow & & \searrow \Rightarrow & \\ \mathrm{DGpoid.} & \xrightarrow{\mathfrak{A}} & & \xrightarrow{\mathfrak{B}} & \end{array}$$

Equivalence of Bicategories

Theorem (continued)

Moreover, we have the following 2-commutative diagram

$$\begin{array}{ccccc} \mathbf{DGpoid}[W^{-1}] & \xrightarrow{\simeq} & \mathbf{DGpoid}_{\text{ana}} & \xrightarrow{\simeq} & \mathbf{DBiBund} \\ \uparrow \mathfrak{G} & \searrow \Rightarrow & & \searrow \Rightarrow & \\ \mathbf{DGpoid.} & \xrightarrow{\mathfrak{A}} & & \xrightarrow{\mathfrak{B}} & \end{array}$$

The Lie Sub-Bicategory

Theorem (W.)

A diffeological weak equivalence between two Lie groupoids is a Lie weak equivalence. (Namely, Ψ_φ in the definition of smooth essential surjectivity is a local subduction = surjective submersion.)

In fact, we can repeat the entire story above using the 2-category of Lie groupoids $\mathbf{LieGpoid}$, and obtain three equivalent bicategories

$$\begin{array}{ccccc} \mathbf{LieGpoid}[W_{\mathbf{Lie}}^{-1}] & \xrightarrow{\simeq} & \mathbf{LieGpoid}_{\text{ana}} & \xrightarrow{\simeq} & \mathbf{LieBiBund} \\ \uparrow \mathfrak{G}|_{\mathbf{Lie}} & \nearrow \Rightarrow & & \nearrow \Rightarrow & \\ \mathbf{LieGpoid} & \xrightarrow{\mathfrak{A}|_{\mathbf{Lie}}} & & \xrightarrow{\mathfrak{B}|_{\mathbf{Lie}}} & \end{array}$$

and all three of these bicategories are essentially full sub-bicategories of their diffeological counterparts.

The Lie Sub-Bicategory

Theorem (W.)

A diffeological weak equivalence between two Lie groupoids is a Lie weak equivalence. (Namely, Ψ_φ in the definition of smooth essential surjectivity is a local subduction = surjective submersion.)

In fact, we can repeat the entire story above using the 2-category of Lie groupoids $\mathbf{LieGpoid}$, and obtain three equivalent bicategories

$$\begin{array}{ccccc} \mathbf{LieGpoid}[W_{\mathbf{Lie}}^{-1}] & \xrightarrow{\simeq} & \mathbf{LieGpoid}_{\text{ana}} & \xrightarrow{\simeq} & \mathbf{LieBiBund} \\ \uparrow \mathfrak{G}|_{\mathbf{Lie}} & \searrow \Rightarrow & \Rightarrow & \searrow \Rightarrow & \\ \mathbf{LieGpoid} & \xrightarrow{\mathfrak{A}|_{\mathbf{Lie}}} & & \xrightarrow{\mathfrak{B}|_{\mathbf{Lie}}} & \end{array}$$

and all three of these bicategories are essentially full sub-bicategories of their diffeological counterparts.

The Lie Sub-Bicategory

Theorem (W.)

A diffeological weak equivalence between two Lie groupoids is a Lie weak equivalence. (Namely, Ψ_φ in the definition of smooth essential surjectivity is a local subduction = surjective submersion.)

In fact, we can repeat the entire story above using the 2-category of Lie groupoids $\mathbf{LieGpoid}$, and obtain three equivalent bicategories

$$\begin{array}{ccccc} \mathbf{LieGpoid}[W_{\mathbf{Lie}}^{-1}] & \xrightarrow{\simeq} & \mathbf{LieGpoid}_{\text{ana}} & \xrightarrow{\simeq} & \mathbf{LieBiBund} \\ \uparrow \mathfrak{G}|_{\mathbf{Lie}} & \nearrow \Rightarrow & & \nearrow \Rightarrow & \\ \mathbf{LieGpoid} & \xrightarrow{\mathfrak{A}|_{\mathbf{Lie}}} & & \xrightarrow{\mathfrak{B}|_{\mathbf{Lie}}} & \end{array}$$

and all three of these bicategories are essentially full sub-bicategories of their diffeological counterparts.

The Lie Sub-Bicategory

Theorem (W.)

A diffeological weak equivalence between two Lie groupoids is a Lie weak equivalence. (Namely, Ψ_φ in the definition of smooth essential surjectivity is a local subduction = surjective submersion.)

In fact, we can repeat the entire story above using the 2-category of Lie groupoids $\mathbf{LieGpoid}$, and obtain three equivalent bicategories

$$\begin{array}{ccccc} \mathbf{LieGpoid}[W_{\mathbf{Lie}}^{-1}] & \xrightarrow{\simeq} & \mathbf{LieGpoid}_{\text{ana}} & \xrightarrow{\simeq} & \mathbf{LieBiBund} \\ \uparrow \mathfrak{G}|_{\mathbf{Lie}} & \nearrow \Rightarrow & & \nearrow \Rightarrow & \\ \mathbf{LieGpoid} & \xrightarrow{\mathfrak{A}|_{\mathbf{Lie}}} & & \xrightarrow{\mathfrak{B}|_{\mathbf{Lie}}} & \end{array}$$

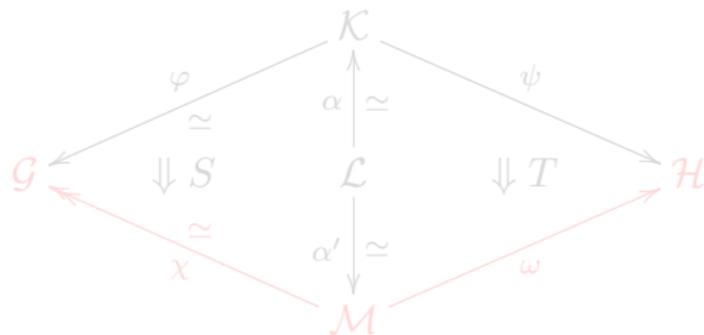
and all three of these bicategories are essentially full sub-bicategories of their diffeological counterparts.

The Lie Sub-Bicategory

- We come back to the question of van der Schaaf: is a diffeological Morita equivalence between Lie groupoids a Lie Morita equivalence?

Corollary

Given a diffeological generalised morphism between Lie groupoids, there is a Lie generalised morphism between them, and a 2-cell between the two generalised morphisms.

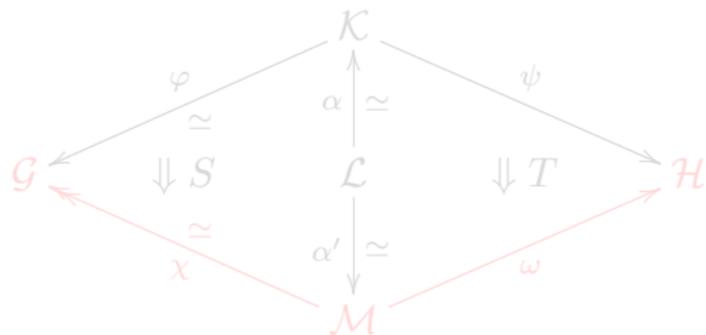


The Lie Sub-Bicategory

- We come back to the question of van der Schaaf: is a diffeological Morita equivalence between Lie groupoids a Lie Morita equivalence?

Corollary

Given a diffeological generalised morphism between Lie groupoids, there is a Lie generalised morphism between them, and a 2-cell between the two generalised morphisms.

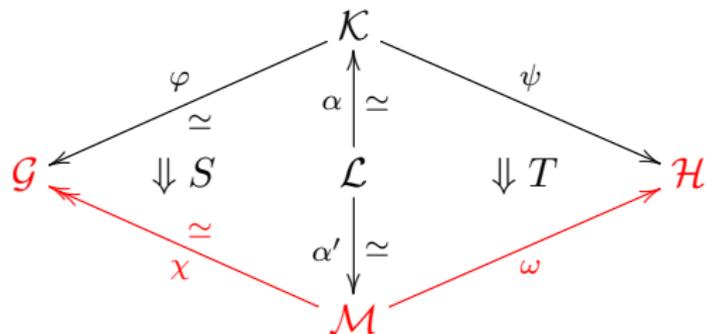


The Lie Sub-Bicategory

- We come back to the question of van der Schaaf: is a diffeological Morita equivalence between Lie groupoids a Lie Morita equivalence?

Corollary

Given a diffeological generalised morphism between Lie groupoids, there is a Lie generalised morphism between them, and a 2-cell between the two generalised morphisms.



“Optimisation”

- Passing from $\mathbf{DGpoid}[W^{-1}]$ to $\mathbf{DGpoid}_{\text{ana}}$ chooses an “optimal” representative of each 2-cell from $\mathbf{DGpoid}[W^{-1}]$: the (unique) transformation in the equivalence class.
- Similarly, passing from $\mathbf{DGpoid}_{\text{ana}}$ to $\mathbf{DBiBund}$ “optimises” an anafunctor to a bibundle: the action groupoid of a bibundle induces an anafunctor.

Question

We are in the realm of diffeology: can we make these “optimisation” processes true optimisation processes? More precisely, can we create a reasonable diffeological space of representatives of a 2-cell from $\mathbf{DGpoid}[W^{-1}]$, and a reasonable diffeological space of anafunctors (or generalised morphisms) between two fixed diffeological groupoids, and make this a true optimisation problem?

“Optimisation”

- Passing from $\mathbf{DGpoid}[W^{-1}]$ to $\mathbf{DGpoid}_{\text{ana}}$ chooses an “optimal” representative of each 2-cell from $\mathbf{DGpoid}[W^{-1}]$: the (unique) transformation in the equivalence class.
- Similarly, passing from $\mathbf{DGpoid}_{\text{ana}}$ to $\mathbf{DBiBund}$ “optimises” an anafunctor to a bibundle: the action groupoid of a bibundle induces an anafunctor.

Question

We are in the realm of diffeology: can we make these “optimisation” processes true optimisation processes? More precisely, can we create a reasonable diffeological space of representatives of a 2-cell from $\mathbf{DGpoid}[W^{-1}]$, and a reasonable diffeological space of anafunctors (or generalised morphisms) between two fixed diffeological groupoids, and make this a true optimisation problem?

“Optimisation”

- Passing from $\mathbf{DGpoid}[W^{-1}]$ to $\mathbf{DGpoid}_{\text{ana}}$ chooses an “optimal” representative of each 2-cell from $\mathbf{DGpoid}[W^{-1}]$: the (unique) transformation in the equivalence class.
- Similarly, passing from $\mathbf{DGpoid}_{\text{ana}}$ to $\mathbf{DBiBund}$ “optimises” an anafunctor to a bibundle: the action groupoid of a bibundle induces an anafunctor.

Question

We are in the realm of diffeology: can we make these “optimisation” processes true optimisation processes? More precisely, can we create a reasonable diffeological space of representatives of a 2-cell from $\mathbf{DGpoid}[W^{-1}]$, and a reasonable diffeological space of anafunctors (or generalised morphisms) between two fixed diffeological groupoids, and make this a true optimisation problem?

“Optimisation”

- Passing from $\mathbf{DGpoid}[W^{-1}]$ to $\mathbf{DGpoid}_{\text{ana}}$ chooses an “optimal” representative of each 2-cell from $\mathbf{DGpoid}[W^{-1}]$: the (unique) transformation in the equivalence class.
- Similarly, passing from $\mathbf{DGpoid}_{\text{ana}}$ to $\mathbf{DBiBund}$ “optimises” an anafunctor to a bibundle: the action groupoid of a bibundle induces an anafunctor.

Question

We are in the realm of diffeology: can we make these “optimisation” processes true optimisation processes? More precisely, can we create a reasonable diffeological space of representatives of a 2-cell from $\mathbf{DGpoid}[W^{-1}]$, and a reasonable diffeological space of anafunctors (or generalised morphisms) between two fixed diffeological groupoids, and make this a true optimisation problem?

- Fix two diffeological groupoids \mathcal{G} and \mathcal{H} . Work in progress indicates that there is a natural diffeology on the groupoid whose objects are a subset of the class of anafunctors from \mathcal{G} to \mathcal{H} , and whose arrows are a subset of the class of 2-cells between these anafunctors (as generalised morphisms).

Work in Progress

- In a joint project with Carla Farsi and Laura Scull (soon to be put on the arXiv), we focus on action groupoids of Lie group actions on manifolds, and show that any generalised morphism between two such groupoids admits a 2-cell to an anafunctor

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ G \times M & \simeq & H \times N \end{array}$$

in which \mathcal{K} is the action groupoid of a $(G \times H)$ -action and φ and ψ are induced by equivariant maps.

- This is accomplished by passing from $\text{LieGpoid}[W^{-1}]$ to $\text{LieGpoid}_{\text{ana}}$ to LieBiBund and then back.
- (This will be important for extending a Bredon cohomology result of Pronk and Scull [PS10] from certain orbifolds to general compact Lie group actions.)

Work in Progress

- In a joint project with Carla Farsi and Laura Scull (soon to be put on the arXiv), we focus on action groupoids of Lie group actions on manifolds, and show that any generalised morphism between two such groupoids admits a 2-cell to an anafunctor

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ G \times M & \simeq & H \times N \end{array}$$

in which \mathcal{K} is the action groupoid of a $(G \times H)$ -action and φ and ψ are induced by equivariant maps.

- This is accomplished by passing from $\mathbf{LieGpoid}[W^{-1}]$ to $\mathbf{LieGpoid}_{\text{ana}}$ to $\mathbf{LieBiBund}$ and then back.
- (This will be important for extending a Bredon cohomology result of Pronk and Scull [PS10] from certain orbifolds to general compact Lie group actions.)

Work in Progress

- In a joint project with Carla Farsi and Laura Scull (soon to be put on the arXiv), we focus on action groupoids of Lie group actions on manifolds, and show that any generalised morphism between two such groupoids admits a 2-cell to an anafunctor

$$\begin{array}{ccc} & \mathcal{K} & \\ \varphi \swarrow & & \searrow \psi \\ G \times M & \simeq & H \times N \end{array}$$

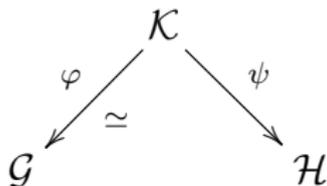
in which \mathcal{K} is the action groupoid of a $(G \times H)$ -action and φ and ψ are induced by equivariant maps.

- This is accomplished by passing from $\mathbf{LieGpoid}[W^{-1}]$ to $\mathbf{LieGpoid}_{\text{ana}}$ to $\mathbf{LieBiBund}$ and then back.
- (This will be important for extending a Bredon cohomology result of Pronk and Scull [PS10] from certain orbifolds to general compact Lie group actions.)

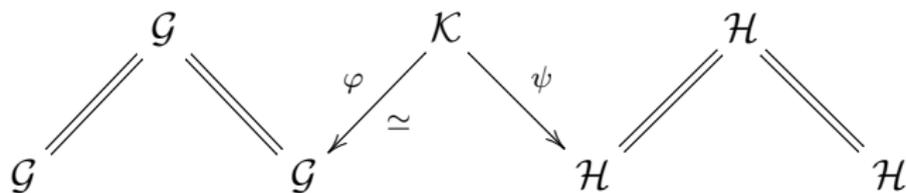
- 1 **DGpoid** $[W^{-1}]$, **DGpoid**_{ana}, and **DBiBund** are all equivalent as bicategories to the 2-category of geometric stacks over diffeological spaces.
- 2 Given a diffeological space X and an abelian diffeological group G , the category of generalised morphisms from X to G is equivalent to $\check{H}^1(X; G)$, the category of diffeological Čech 1-cocycles with 0-chains in between. This, in turn, is equivalent to principal G -bundles over X with bundle isomorphisms in between. (See [KWW21].)
- 3 If X is such that all principal G -bundles are D-numerable, then this category is also equivalent to $[X, BG]$, comprising smooth maps $X \rightarrow BG$ with smooth homotopies in between. (See [CW21, MW17].)

- 1 $\mathbf{DGpoid}[W^{-1}]$, $\mathbf{DGpoid}_{\text{ana}}$, and $\mathbf{DBiBund}$ are all equivalent as bicategories to the 2-category of geometric stacks over diffeological spaces.
- 2 Given a diffeological space X and an abelian diffeological group G , the category of generalised morphisms from X to G is equivalent to $\check{H}^1(X; G)$, the category of diffeological Čech 1-cocycles with 0-chains in between. This, in turn, is equivalent to principal G -bundles over X with bundle isomorphisms in between. (See [KWW21].)
- 3 If X is such that all principal G -bundles are D-numerable, then this category is also equivalent to $[X, BG]$, comprising smooth maps $X \rightarrow BG$ with smooth homotopies in between. (See [CW21, MW17].)

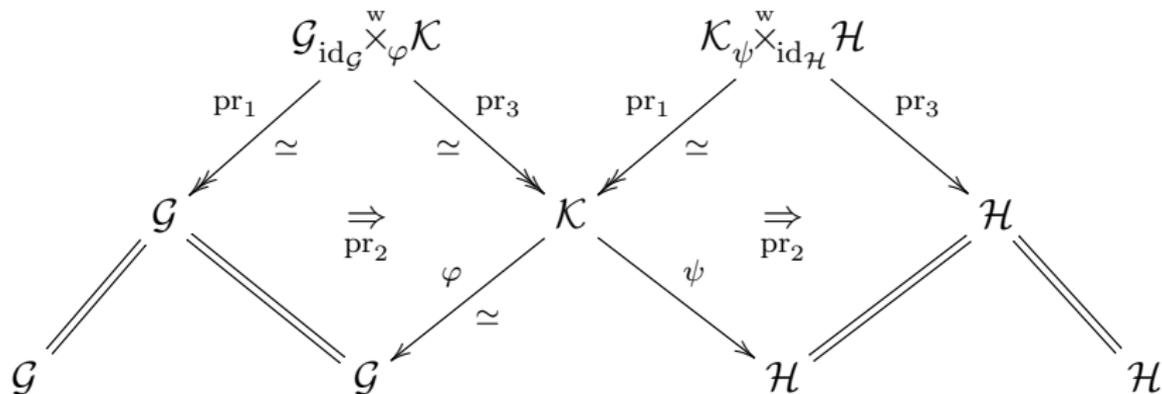
Construction: Generalised Morphism to Bibundle



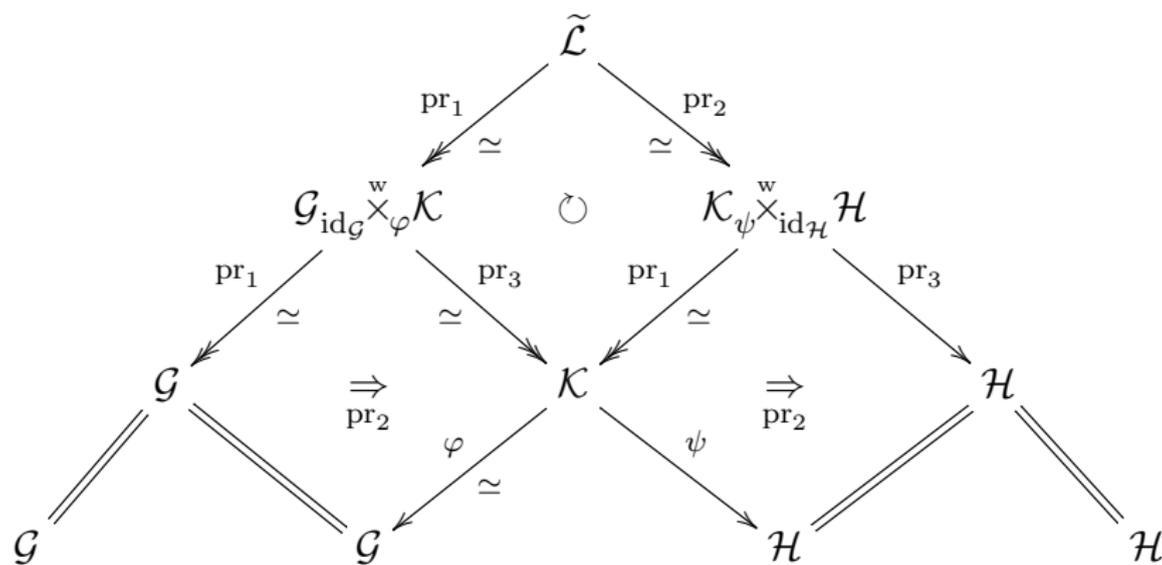
Construction: Generalised Morphism to Bibundle



Construction: Generalised Morphism to Bibundle



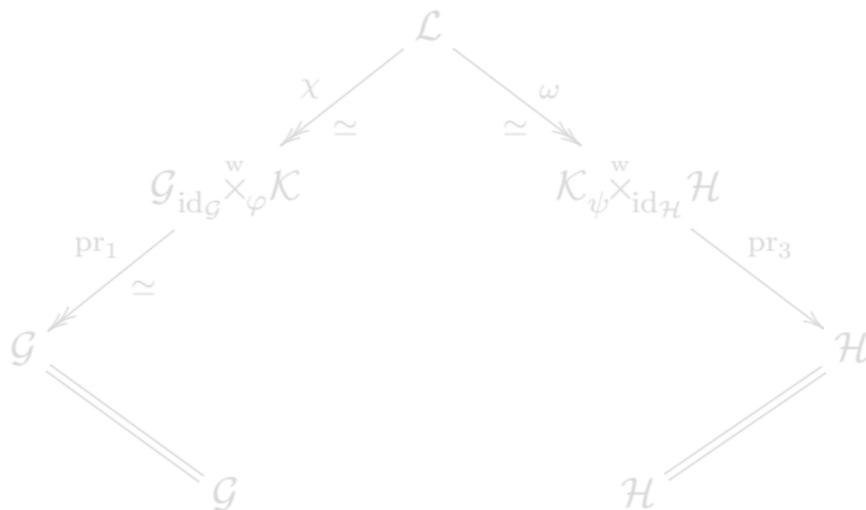
Construction: Generalised Morphism to Bibundle



where $\tilde{\mathcal{L}} = (\mathcal{G}_{\text{id}_{\mathcal{G}}} \times_{\varphi}^w \mathcal{K})_{\text{pr}_3} \times_{\text{pr}_1} (\mathcal{K} \times_{\psi}^w \text{id}_{\mathcal{H}})$.

Construction: Generalised Morphism to Bibundle

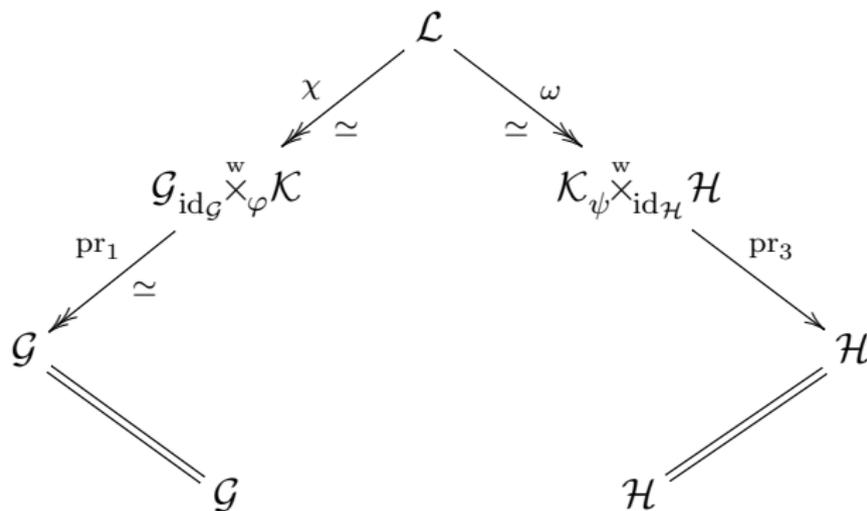
$\tilde{\mathcal{L}}$ comes equipped with a left and a right \mathcal{K} -action. Let $\mathcal{L} := \mathcal{K} \backslash \tilde{\mathcal{L}} / \mathcal{K}$.



\mathcal{L} is isomorphic as a groupoid to the action groupoid of a bibundle from \mathcal{G} to \mathcal{H} .

Construction: Generalised Morphism to Bibundle

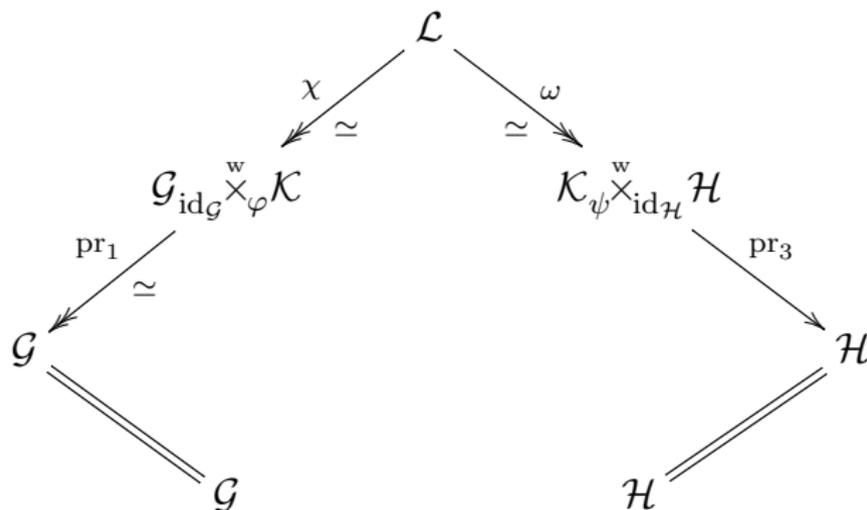
$\tilde{\mathcal{L}}$ comes equipped with a left and a right \mathcal{K} -action. Let $\mathcal{L} := \mathcal{K} \backslash \tilde{\mathcal{L}} / \mathcal{K}$.



\mathcal{L} is isomorphic as a groupoid to the action groupoid of a bibundle from \mathcal{G} to \mathcal{H} .

Construction: Generalised Morphism to Bibundle

$\tilde{\mathcal{L}}$ comes equipped with a left and a right \mathcal{K} -action. Let $\mathcal{L} := \mathcal{K} \backslash \tilde{\mathcal{L}} / \mathcal{K}$.



\mathcal{L} is isomorphic as a groupoid to the action groupoid of a bibundle from \mathcal{G} to \mathcal{H} .

Thank you!

References

- AZ20** Iakovos Androulidakis and Marco Zambon, "Integration of singular subalgebroids", 2020 (preprint).
- BFW13** Christian Blohmann, Marco Cezar Barbosa Fernandes, and Alan Weinstein, "Groupoid symmetry and constraints in general relativity", *Commun. Contemp. Math.*, 1.1250061 (2013).
- CW21** J. Dan Christensen and Enxin Wu, "Smooth classifying spaces", *Israel J. Math.* **241** (2021), 911–954.
- GV21** Alfonso Garmendia and Joel Villatoro, "Integration of singular foliations via paths", 2021 (preprint).
- KWW21** Derek Krepski, Jordan Watts, and Seth Wolbert, "Sheaves, principal bundles, and Čech cohomology for diffeological spaces, 2021 (preprint).
- MW17** Jean-Pierre Magnot and Jordan Watts, "The diffeology of Milnor's classifying space", *Topol. Appl.* **232** (2017), 189–213.
- MP97** Ieke Moerdijk and Dorette Pronk, "Orbifolds, sheaves and groupoids", *K-Theory* **12** (1997), 3–21.
- P96** Dorette Pronk, "Etendues and stacks as bicategories of fractions", *Compos. Math.*, **102** (1996), 243–303.
- PS10** Dorette Pronk and Laura Scull, "Translation groupoids and orbifold cohomology", *Canad. J. Math.* **62** (2010), 614–645.
- R21** David Michael Roberts, "The elementary construction of formal anafunctors", *Categ. Gen. Algebr. Struct.*, **15** (2021), 183–229.
- RV18** David Michael Roberts and Raymond F. Vozzo, "Smooth loop stacks of differentiable stacks and gerbes", *Cah. Topol. Géom. Différ. Catég.*, **59** (2018), 95–141.

- PS21 Dorette Pronk and Laura Scull, "Bicategories of fractions revisited: towards small Homs and canonical 2-cells", 2021 (preprint).
- vdS20 Nesta van der Schaaf, *Diffeology, Groupoids & Morita Equivalence*, Master's thesis, Radboud University, 2020.
- vdS21 Nesta van der Schaaf, "Diffeological Morita Equivalence", *Cah. Topol. Géom. Différ. Catég.*, **LXII-2** (2021), 177–238.

- W Jordan Watts, "Bicategories of Diffeological Groupoids", 2022 (preprint).